

Module 4. Superposition theorem for circuits. Transformers

Circuit Theory, GIT
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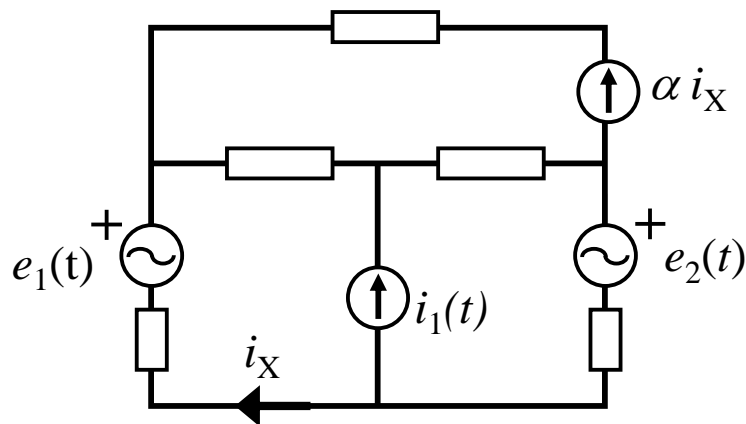
Fundamental theorems

- Superposition theorem
 - Principle of superposition
 - Multiplication by a constant
- Transformers
 - Real transformer
 - Perfect transformer
 - Ideal transformer

Principle of superposition

- Any linear circuit can be solved by considering each independent source acting by it's own:
 - Solve the circuit for each independent source
 - The solution of the global circuit is then the superposition of de solutions obtained by each source

Example 1:



$$e_1(t) = |E_1| \sin(\omega_1 t + \phi_1),$$

$$i_1(t) = |I_1| \sin(\omega_1 t + \theta_2),$$

$$e_2(t) = |E_2| \sin(\omega_2 t + \phi_2)$$

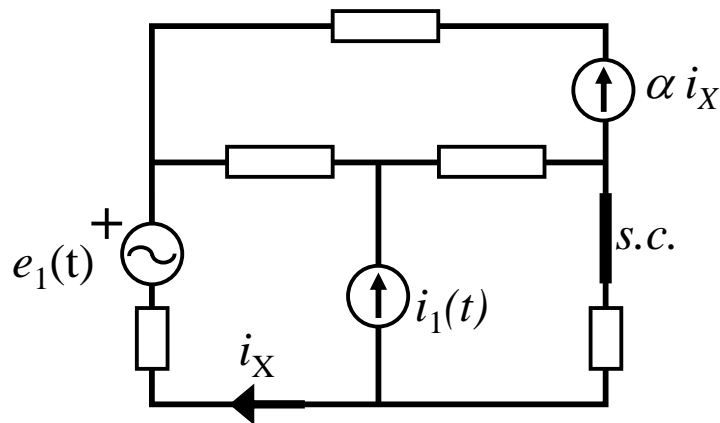
Principle of superposition

- One circuit for each source of the same temporal behavior (e.g. the same frequencies)
- **Independent sources of different temporal behavior are annulled:**
 - Voltage sources replaced by s.c.
 - Current sources replaced by o.c.
- (Dependent sources are not annulled)

Principle of superposition

- Example 1: Two different kind of sources (ω_1, ω_2)

Circuit with sources of frequency $\omega = \omega_1$

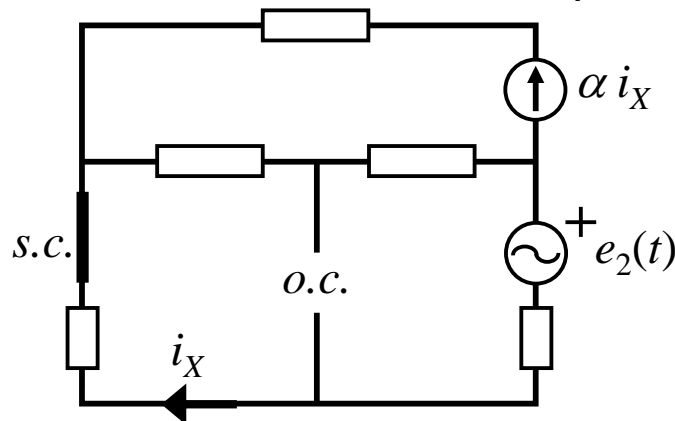


$$e_1(t) = |E_1| \sin(\omega_1 t + \phi_1),$$

$$i_1(t) = |I_1| \sin(\omega_1 t + \theta_2),$$

$$e_2(t) = 0$$

Circuit with sources of frequency $\omega = \omega_2$



$$e_1(t) = 0,$$

$$i_1(t) = 0,$$

$$e_2(t) = |E_2| \sin(\omega_2 t + \phi_2)$$

Principle of superposition

- Each circuit is solved independently for each temporal behavior (e.g. same frequency)
- For the **global circuit**:
 - The solution for the currents and voltages are added in the **time domain**:

$$i(t) = i(t)|_{\omega_1} + i(t)|_{\omega_2} + \dots$$

$$v(t) = v(t)|_{\omega_1} + v(t)|_{\omega_2} + \dots$$

This means obtained in the circuit with only sources of frequency ω_2

- The power delivered or dissipated by a **dependen source** is the addition of the power calculated in each circuit with a specific frequency:

$$P_{\text{dependen source}} = P_{\text{dependen source}}|_{\omega_1} + P_{\text{dependen source}}|_{\omega_2} + \dots$$

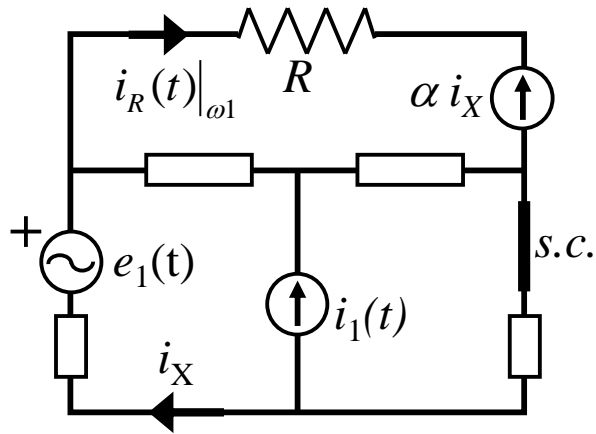
- The power of an **independen source** of frequency ω_1 is calculated only for the circuit with sources of the same frequency:

$$P_{\text{independen source of frequency } \omega_1} = P_{\text{independen source}}|_{\omega_1}$$

Principle of superposition

- Example 1: Two different kind of sources (ω_1, ω_2)

Circuit with sources of frequency $\omega = \omega_1$



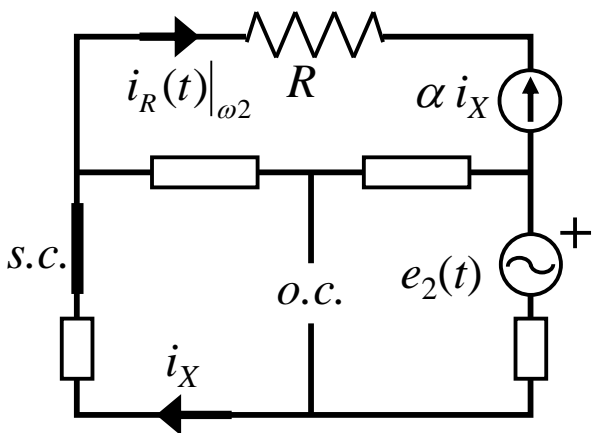
$$i_R(t)|_{\omega_1} = |I_1| \sin(\omega_1 t + \theta_1)$$

$$P_R|_{\omega_1} = \frac{1}{2} |I_R|_{\omega_1}^2 R$$

$$P_{\alpha i_x}|_{\omega_1}$$

$$P_{e_1} = P_{e_1}|_{\omega_1}$$

Circuit with sources of frequency $\omega = \omega_2$



$$i_R(t)|_{\omega_2} = |I_2| \sin(\omega_2 t + \theta_2)$$

$$P_R|_{\omega_2} = \frac{1}{2} |I_R|_{\omega_2}^2 R$$

$$P_{\alpha i_x}|_{\omega_2}$$

$$P_{e_2} = P_{e_2}|_{\omega_2}$$

Superposition:

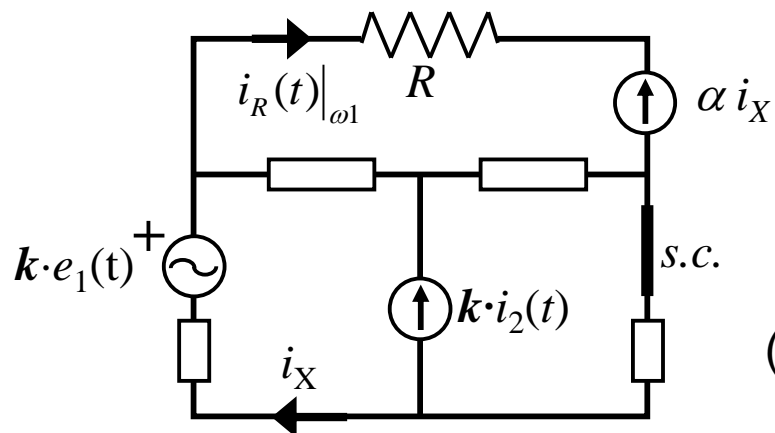
$$\left\{ \begin{aligned} i_R(t) &= |I_1| \sin(\omega_1 t + \theta_1) + \\ &\quad |I_2| \sin(\omega_2 t + \theta_2) \\ P_R &= P_R|_{\omega_1} + P_R|_{\omega_2} \\ P_{\alpha i_x} &= P_{\alpha i_x}|_{\omega_1} + P_{\alpha i_x}|_{\omega_2} \end{aligned} \right.$$

It can be used to separately analyze the DC and AC behavior of a circuit

Multiplication by a constant

- In a linear circuit, if **all the independent sources** with the same temporal behavior are multiplied by a constant, **k** , then the current (or voltage) along any wire (or between any two points) in the circuit is multiplied by the same constant.

Example 1. Circuit with sources of frequency $\omega = \omega_1$ are multiply by **k**



You only need to multiply by **k** the previous result

$$i_R(t) = \mathbf{k} |I_1| \sin(\omega_1 t + \theta_1) + |I_2| \sin(\omega_2 t + \theta_2)$$

(The previous calculated powers vary accordingly)

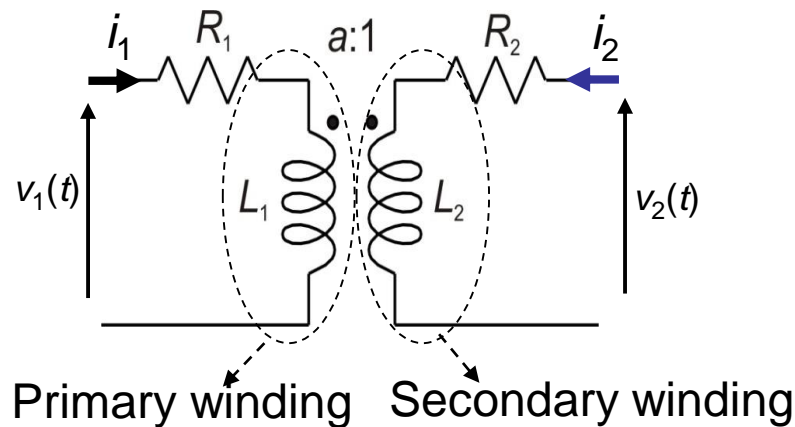


Transformers



Real transformer

- The transformers transfer electrical energy from one circuit to another one through magnetically coupled coils



$$\begin{cases} R_1, R_2 \neq 0 \\ K \neq 1 \\ N_1, N_2 \text{ are finite} \end{cases}$$

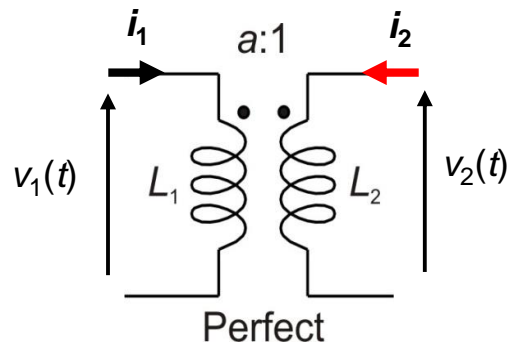
$$a = \frac{N_1}{N_2} \text{ is the } \mathbf{turn\ ratio}$$

$$\begin{cases} v_1(t) = \left(R_1 + L_1 \frac{d}{dt} \right) i_1(t) + M_{12} \frac{d}{dt} i_2(t) \\ v_2(t) = M_{12} \frac{d}{dt} i_1(t) + \left(R_2 + L_2 \frac{d}{dt} \right) i_2(t) \end{cases}$$



Perfect transformer

- The coupling coefficient is one and the number of turns are finite



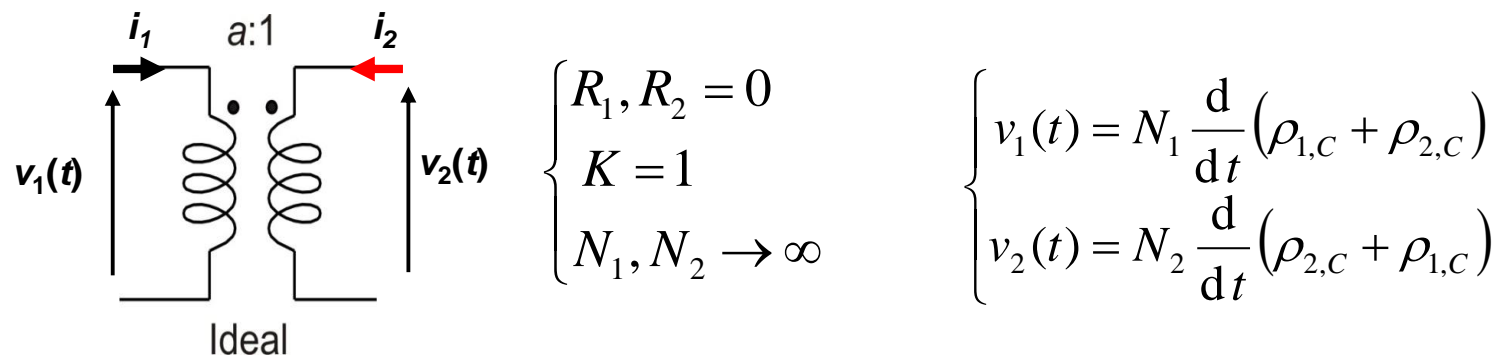
$$\begin{cases} R_1, R_2 = 0 \\ K = 1 \rightarrow \rho_S \cong 0 \\ N_1, N_2 \text{ are finite} \end{cases}$$

$$\begin{cases} v_1(t) = N_1 \frac{d}{dt} (\rho_{1,c} + \rho_{2,c}) \\ v_2(t) = N_2 \frac{d}{dt} (\rho_{2,c} + \rho_{1,c}) \end{cases} \Rightarrow \frac{v_1(t)}{v_2(t)} = \frac{N_1}{N_2} = \sqrt{\frac{L_1}{L_2}} = a.$$



Ideal transformer

- The coupling coefficient is one and the number of turns are infinite (but not the turn ratio)



- For Sinusoidal Steady State:

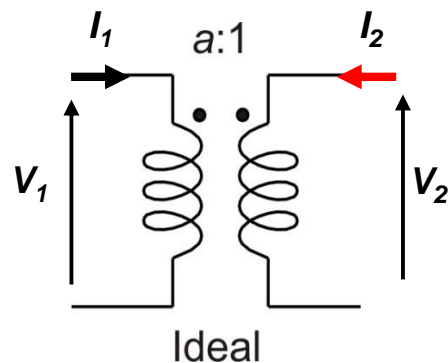
$$\left\{ \begin{array}{l} V_1 e^{j\omega t} = N_1 \frac{d}{dt} (\Phi_{1,c} e^{j\omega t} + \Phi_{2,c} e^{j\omega t}) = j\omega N_1 (\Phi_{1,c} + \Phi_{2,c}) e^{j\omega t} \\ V_2 e^{j\omega t} = N_2 \frac{d}{dt} (\Phi_{2,c} e^{j\omega t} + \Phi_{1,c} e^{j\omega t}) = j\omega N_2 (\Phi_{2,c} + \Phi_{1,c}) e^{j\omega t} \end{array} \right.$$

∞ \nearrow $\underbrace{\hspace{10em}}_0$



Ideal transformer

- The magnetic flux within the core becomes zero



$$\Phi_C = \Phi_{1C} + \Phi_{2C} \rightarrow 0$$

$$\Rightarrow \frac{N_1}{\mathcal{R}_C} I_1 + \frac{N_2}{\mathcal{R}_C} I_2 = 0$$

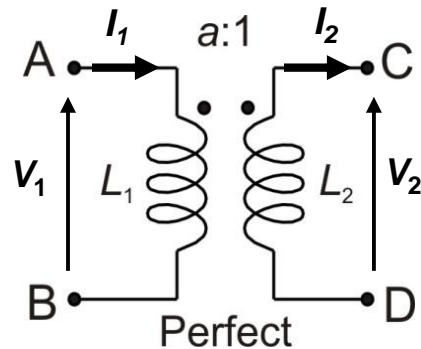
$$\Rightarrow I_2 = -\frac{N_1}{N_2} I_1$$

The mutual induced current in the secondary winding generates a magnetic flux that opposes and cancels the magnetic flux generated by the primary winding \Rightarrow The intensity exiting the dot at the secondary winding (I_2) is a -times the intensity entering through the dot of the primary winding (I_1).

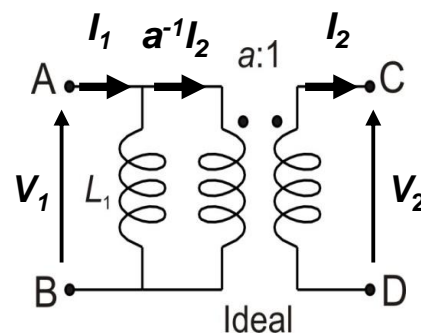


Perfect to Ideal transformer

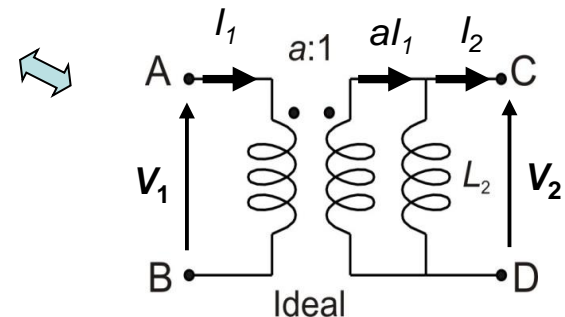
- Perfect transformer has an equivalent ideal transformer in parallel with an inductor



$$\begin{cases} V_1 = j\omega L_1 I_1 - j\omega M_{12} I_2 \\ V_2 = -j\omega L_2 I_2 + j\omega M_{12} I_1 \\ a = \sqrt{\frac{L_1}{L_2}}, M_{12} = \sqrt{L_1 L_2} \Rightarrow M_{12} = L_1 \frac{1}{a} = L_2 a \end{cases}$$



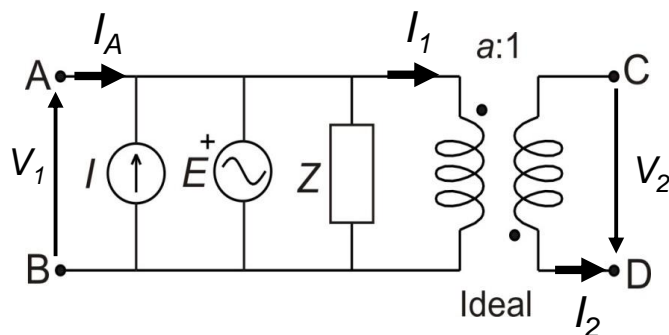
$$\Rightarrow \begin{cases} V_1 = j\omega L_1 \left(I_1 - \frac{1}{a} I_2 \right) \\ V_2 = j\omega L_2 (a I_1 - I_2) \end{cases}$$





Operating with ideal transformers

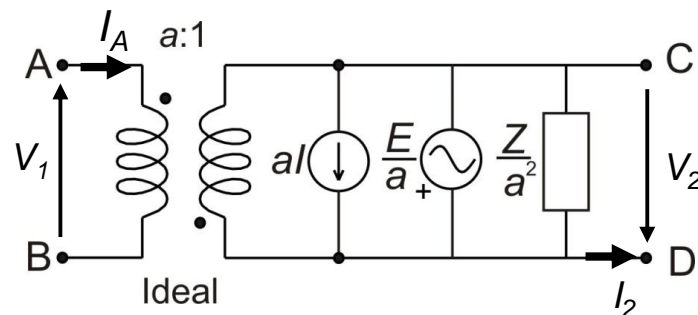
- We can “move” elements from one side of the ideal transformer to the other side as follows



$$\begin{cases} I_2 = aI_1 \\ V_2 = \frac{1}{a}V_1 \end{cases}$$

which is equivalent to:

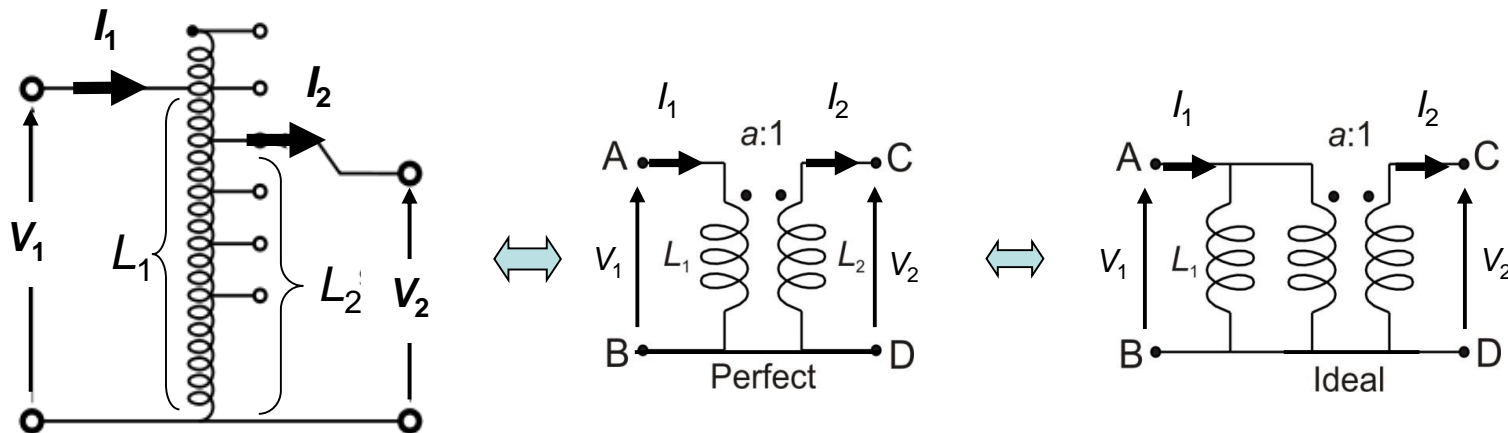
Note: If the dot's are crossed the direction of the electrical sources change





Autotransformer

- It is a perfect transformer with only one winding. Portions of the same winding act as both the primary and secondary winding ($k=1$)



$$V_{AC} = V_1 - V_2 = V_1 \left(1 - \frac{1}{a} \right) \text{ is called the isolation voltage}$$